# **URS-B Series**

# Precision Rotation Stage











USER'S MANUAL

# Warranty

Newport Corporation warrants this product to be free from defects in material and workmanship for a period of 1 year from the date of shipment. If found to be defective during the warranty period, the product will either be repaired or replaced at Newport's discretion.

To exercise this warranty, write or call your local Newport representative, or contact Newport headquarters in Irvine, California. You will be given prompt assistance and return instructions. Send the instrument, transportation prepaid, to the indicated service facility. Repairs will be made and the instrument returned, transportation prepaid. Repaired products are warranted for the balance of the original warranty period, or at least 90 days.

# **Limitation of Warranty**

This warranty does not apply to defects resulting from modification or misuse of any product or part.

# **CAUTION**

Warranty does not apply to damages resulting from:

- Incorrect usage:
  - Load on the stage greater than maximum specified load.
  - Carriage speed higher than specified speed.
  - Improper grounding.
    - ¬ Connectors must be properly secured.
    - ¬ When the load on the stage represents an electrical risk, it must be connected to ground.
  - Excessive or improper cantilever loads.
- Modification of the stage or any part thereof.

This warranty is in lieu of all other warranties, expressed or implied, including any implied warranty of merchantability or fitness for a particular use. Newport Corporation shall not be liable for any indirect, special, or consequential damages.

No part of this manual may be reproduced or copied without the prior written approval of Newport Corporation.

This manual has been provided for information only and product specifications are subject to change without notice. Any changes will be reflected in future printings.



# **CAUTION**

Please return equipment in the original (or equivalent) packing.

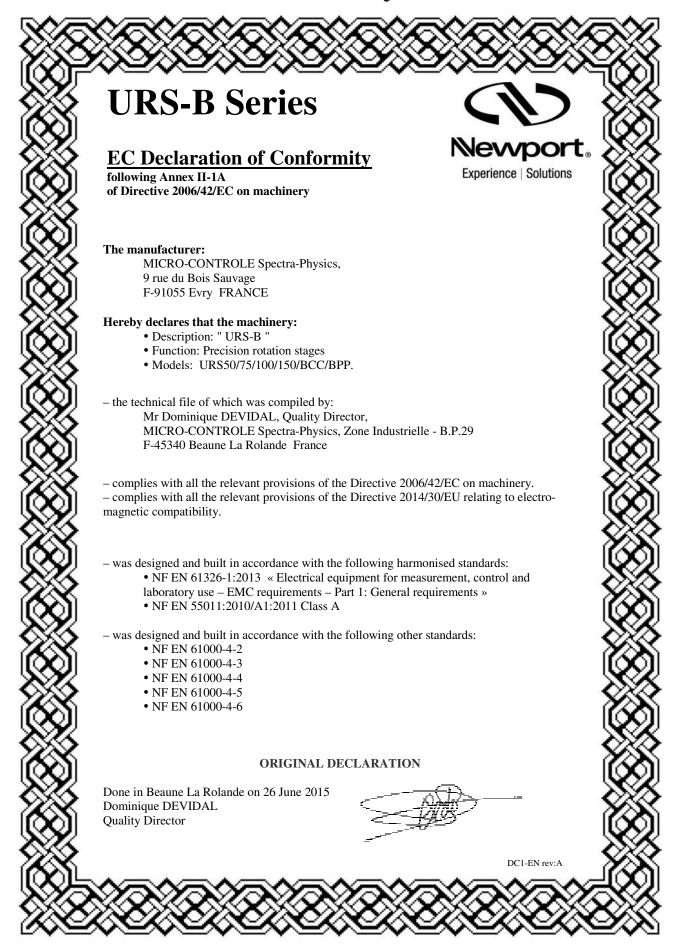
You will be responsible for damage incurred from inadequate packaging if the original packaging is not used.

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# **EC Declaration of Conformity**



# **Definitions and Symbols**

The following terms and symbols are used in this documentation and also appear on the product where safety-related issues occur.

### **General Warning or Caution**



The exclamation symbol may appear in warning and caution tables in this document. This symbol designates an area where personal injury or damage to the equipment is possible.

The following are definitions of the Warnings, Cautions and Notes that may be used in this manual to call attention to important information regarding personal safety, safety and preservation of the equipment, or important tips.



#### **WARNING**

Warning indicates a potentially dangerous situation which can result in bodily harm or death.



#### **CAUTION**

Caution indicates a potentially hazardous situation which can result in damage to product or equipment.

#### **NOTE**

Note indicates additional information that must be considered by the user or operator.

### **European Union CE Mark**



The presence of the CE Mark on Newport Corporation equipment means that it has been designed, tested and certified as complying with all applicable European Union (CE) regulations and recommendations.

### **Warnings and Cautions**



# **ATTENTION**

This stage is a Class A device. In a residential environment, this device can cause electromagnetic interference. In this case, suitable measures must be taken by the user.

# Warnings



#### WARNING

The motion of objects of all types carries potential risks for operators. Ensure the protection of operators by prohibiting access to the dangerous area and by informing the personnel of the potential risks involved.

#### **WARNING**

Do not use this stage when its motor is emitting smoke or is unusually hot to the touch or is emitting any unusual odor or noise or is in any other abnormal state.

Stop using the stage immediately, switch off the motor power and then disconnect the electronics power supply.

After checking that smoke is no longer being emitted contact your Newport service facility and request repairs. Never attempt to repair the stage yourself as this can be dangerous.

#### WARNING

Make sure that this stage is not exposed to moisture and that liquid does not get into the stage.

Nevertheless, if any liquid has entered the stage, switch off the motor power and then disconnect the electronics from power supply.

Contact your Newport service facility and request repairs.





Do not insert or drop objects into this stage, this may cause an electric shock, or lock the drive.

Do not use this stage if any foreign objects have entered the stage. Switch off the motor power and then disconnect the electronics power supply.

Contact your Newport service facility for repairs.

#### WARNING

Do not place this stage in unstable locations such as on a wobbly table or sloping surface, where it may fall or tip over and cause injury.

If this stage has been dropped or the case has been damaged, switch off the motor power and then disconnect the electronics power supply.

Contact your Newport service facility and request repairs.

#### WARNING

Do not attempt to modify this stage; this may cause an electric shock or downgrade its performance.

# WARNING

Do not exceed the usable depth indicated on the mounting holes (see section "Dimensions"). Longer screws can damage the mechanics or cause a short-circuit.

# **Cautions**

#### **CAUTION**

Do not place this stage in a hostile environment such as X-Rays, hard UV,... or in any vacuum environment.

#### **CAUTION**

Do not place this stage in a location affected by dust, oil fumes, steam or high humidity. This may cause an electric shock.

#### **CAUTION**

Do not leave this stage in places subject to extremely high temperatures or low temperatures. This may cause an electric shock.

- Operating temperature: +10 to +35 °C
- Storage temperature: -10 to +40 °C (in its original packaging)

### **CAUTION**



Do not move this stage if its motor power is on.

Make sure that the cable to the electronics is disconnected before moving the stage. Failure to do so may damage the cable and cause an electrical shock.

#### **CAUTION**

Be careful that the stage is not bumped when it is being carried. This may cause it to malfunction.

#### **CAUTION**

When handling this stage, always unplug the equipment from the power source for safety.

#### **CAUTION**

When the carriage is in its end-of-run position, it is strongly recommended not to go beyond this point as this may damage the stage mechanism.

#### **CAUTION**

Contact your Newport service facility to request cleaning and specification control every year.

# Precision Rotation Stages URS-B Series

1.0

# Introduction

This manual provides operating instructions for the URS-B series rotation stages:

• URS-BCC

• URS-BPP



URS75BCC rotation stage.

### RECOMMENDATION

We recommend you read carefully the chapter "Connection to electronics" before using the URS-B rotation stage.

2.0

# **Description**

The URS-B Series provides precision 360° continuous motion in a low profile package. They meet the requirements of numerous research and industrial applications and may be assembled directly with Newport's VP (URS75B), XM, GTS, ILS (URS100B), IMS (URS100B and URS150B) and other series of linear stages. URS-B rotation stages are available in two versions:

- The URS75BCC to URS150BCC DC-motor versions features an ultra-high resolution 8,000 cts/rev rotary encoder with index pulse for precision homing and is the recommended choice for applications requiring accurate bi-directional positioning. For the tightest position control, the rotary encoder is mounted directly on the worm screw. This eliminates most of the possible error sources associated with indirect read feedback devices. The high-torque of some DC motor versions provides the highest dynamic speed range and allows for rotating speeds up to 80 °/s. The URS50BCC DC-version is our smallest version and its motor encoder feature provides a very compact and easy to integrate version which can go up to 20 °/s with 100 N maximum load capacity.
- The stepper motor version is a more economical version for less demanding applications. When used with motion controllers with high micro-step capability, like the XPS or ESP301, low noise operation and very small incremental motions are guaranteed. The stepper motor versions do not use encoder feedback, but reach a position by the number of commanded steps and microsteps. For this purpose, the stepper motor is directly attached to the worm screw using a proprietary bellows coupling that has a high torsional stiffness, eliminating the need for a gear or belt drive. The high output torque of the stepper motor minimizes the risk of lost steps and provides good linearity between commanded microsteps and the actual motion of the stage.

Furthermore, except for the URS50B stages, all other versions feature adjustable limit switches to prevent over travel.

All URS-B rotation stages feature a proprietary ball bearing to provides a low-profile compact stage with exceptional stiffness, high reliability and outstanding wobble and eccentricity. The tilted worm screw arrangement allows for 4 symmetric mounting holes as compared to other designs that only feature 2 or 3 mounting holes. This enables the URS-B stages to provide better support of higher or off-centered loads. Additionally, the flexible preloading system for the worm gear was improved to guarantee a backlash-free operation with an MTBF of 20,000 hours.

# 2.1 Design Details

Based Material	Hardened steel body				
Bearings	Large diameter ball bearings				
Drive Mechanism	URS50BCC: Gearbox 1:14, no belt.				
	URS75B to URS150B: Ground worm gear with self-compensating preload.				
	Additional 1:2.75 drive belt with URS75BCC to URS150BCC versions				
	(no belt on URS-BPP versions)				
Worm Gear Ratio	URS50B: 1:80				
	URS75B to URS150B: 1:90				
Feedback	URS50BCC: Encoder at motor rear, no index pulse				
	URS75BCC to URS150BCC: Worm mounted 8,000 cts/rev encoder, index pulse				
	URS-BPP: None				
Limit Switches	Two independently adjustable optical limit switches (Except URS50B)				
Origin	Optical, fixed at position 0°. Typical 0.0005° repeatability for URS-BCC				
	and 0.04° repeatability for URS-BPP				
Manual Adjustment	Via allen wrench at the end of the worm screw. Allen wrench is included.				
Motor	URS50BCC: UE18CC DC servo motor				
	URS75BCC to URS150BCC: UE34CC DC servo motor				
	URS50BPP: UE28PP Two phase stepper motor, 1 full step = $0.0225^{\circ}$				
	URS75BPP to URS150BPP: UE34PP Two phase stepper motor, 1 full step = $0.02^{\circ}$				
Cable	3 m long cable included				



## **NOTE**

This product complies with the RoHS directive (Restriction of Hazardous Substances).



### **Characteristics**

#### 3.1 Definitions

Specifications of our products are established in reference to ISO 230 standard part II "Determination of accuracy and repeatability of positioning numerically controlled axes".

This standard gives the definition of position uncertainty which depends on the 3 following parameters:

#### (Absolute) Accuracy

Difference between ideal position and real position.

#### **On-Axis Accuracy**

Difference between ideal position and real position after the compensation of linear errors.

Linear errors include: cosine errors, inaccuracy of screw or linear scale pitch, angular deviation at the measuring point (Abbe error) and thermal expansion effects. All Newport motion electronics can compensate for linear errors.

The relation between absolute accuracy and on-axis accuracy is as follows:

Absolute Accuracy = On-Axis Accuracy + Correction Factor x Travel

#### Repeatability

Ability of a system to achieve a commanded position over many attempts.

#### **Reversal Value (Hysteresis)**

Difference between actual position values obtained for a given target position when approached from opposite directions.

## **Minimum Incremental Motion (MIM or Sensitivity)**

The smallest increment of motion a device is capable of delivering consistently and reliably.

#### Resolution

The smallest increment that a motion device can theoretically move and/or detect. Resolution is not achievable, whereas MIM, is the real output of a motion system.

### **Eccentricity**

Displacement of the geometric center of a rotation stage from the rotation axis in the plane defined by bearings.

#### **Wobble**

Tilt of rotation axis during rotation of a stage, measured on a reference surface.

The testing of on-axis accuracy, repeatability, and reversal error are made systematically with test equipment in an air-conditioned room ( $20^{\pm 1}$  °C).

A linear cycle with 21 data points on the travel and 4 cycles in each direction gives a total of 164 points.

# **Guaranteed Specifications**

Guaranteed maximum performance values are verified per Newport's A167 metrology test procedure. For more information, please consult the metrology tutorial section in the Newport catalog or at **www.newport.com** 

# 3.2 Mechanical Specifications

	URS50BPP	URS50BCC	URS75BPP to URS150BPP	URS75BCC to URS150BCC
Travel Range (°)		360 cont	tinuous <sup>(1)</sup>	
Minimum Incremental Motion (°)	0.0005	0.001	0.0002	0.002
Uni-directional Repeatability (2) (°)	0.002	0.002	0.002	0.002
Bi-directional Repeatability (2) (°)	0.008 or ± 0.004	0.006 or ± 0.003	0.02 or ± 0.01	0.006 or ± 0.003
Absolute Accuracy (2) (°)	0.05 or ± 0.025	0.04 or ± 0.02	0.030 or ± 0.015	0.023 or ± 0.0115
Maximum Speed (°/s)	40 (4)	20	40	80
Wobble (2) (µrad)		50 oı	± 25	
Eccentricity (2) (µm)	6 or ± 3	6 or ± 3	3 or ± 1.5	3 or ± 1.5
MTBF	2	0000 h @ 25% load	and a 30% duty cyc	cle



- 1) With disabled limit switches.
- <sup>2)</sup> Shown are peak to peak, guaranteed specifications or ±half the value as sometimes shown. For the definition of typical specifications which are about 2X better than the guaranteed values, visit www.newport.com for the Motion Control Metrology Primer.



#### **CAUTION**

To reach specifications stated, stages must be fixed on a plane surface with a flatness of 5  $\mu m.$ 

# 3.3 Load Specification Definitions

### **Normal Load Capacity (Cz)**

Maximum load a rotation stage can move while maintaining specifications.

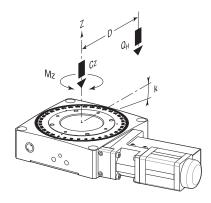
This value is given with speed and acceleration specified for each rotation stage, and with a load perpendicular to bearings.

# Off-Centered Load (Q)

Maximum cantilever-load a rotation stage can move: Q ≤Cz ÷ (1 + D/a)

- D: Cantilever distance.
- a: Construction parameter.

# 3.4 Load Characteristics and Stiffness



	UKS50B	URS75B	UKS100B	URS150C
Cz, Normal centered load capacity (N)	100	200	300	300
a, Construction parameter (mm)	20	25	35	55
Kα, Transversal compliance (μrad/Nm)	100	30	10	5
Mz, Nominal torque (Nm)	±0.25	±0.5	±1	±2
Q, Off-center load (N)		Q≤Cz÷	(1 + D/a)	
Where D = Cantilever distance (mm)				

# 3.5 Stage Weights

Weights indicated into the below table are average values without any cable.

	Weight [lb (kg)]
URS50B	1.5 (0.7)
URS75B	3.7 (1.7)
URS100B	4.4 (2.0)
URS150B	7.5 (3.4)
3-meter MSCABLE-3 Cable	0.66 (0.3)

The weight difference between drive units is not significant.

# 1.0 Drive

#### 4.1 DC-Motor Drives

	Resolution (°)	Speed (°/s)	Motor
URS50BCC	0.00016	20	UE18CC-R2
URS75 to 150BCC	0.0005	80	UE34CC

# 4.2 Stepper Motor Drives

Full-Step
Resolution (1) Speed
(°) (°/s) Motor

URS50BPP 0.0225 40 UE28PP
URS75 to 150BPP 0.02 40 UE34PP

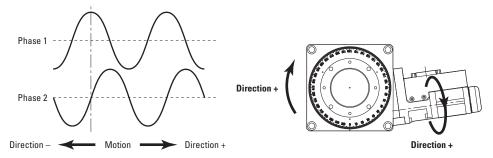
<sup>&</sup>lt;sup>1)</sup> When used with Newport motion controllers, these motors are driven in a dynamic micro-stepping mode (software commutation). In this case, the mechanical sensitivity is approx. 1/100 of a full step.

# **Motor**

# **5.1** Stepper Motor Characteristics

Motor	Angle by Step	RMS Current per	Resistance	Inductance	Newport
MOTOL	(°)	Phase (A)	$(\Omega)$	(mH)	Utilization
UE28PP	1.8	0.71	2.5	1.6	Micro-step
UE34PP	1.8	0.71	1.7	2.8	Micro-step

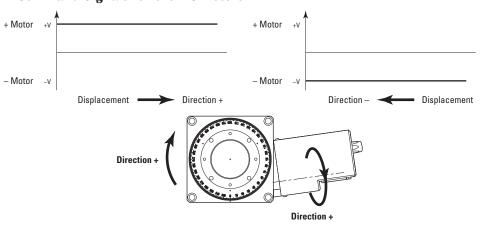
# 5.2 Command Signals for the Stepper Motors



## 5.3 DC-Motor Characteristics

Motor	Nominal	Max. RMS	Max. Peak	Resistance	Inductance
	Voltage (V)	Current (A)	Current (A)	$(\Omega)$	(mH)
UE18CC-R2	24	0.15	0.21	54.6	1.2
UE34CC	48	0.9	1.8	2.52	0.51

# 5.4 Command Signals for the DC-Motors



In the above drawings, + Motor signal is referenced to - Motor signal.

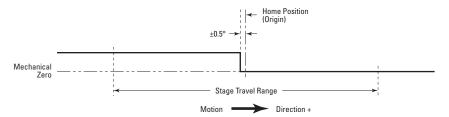
- ① When the stage moves in + Direction, the + Motor voltage is higher than Motor voltage.
- ② When the stage moves in Direction, the + Motor voltage is lower than Motor voltage.

### 5.5 Sensor Position

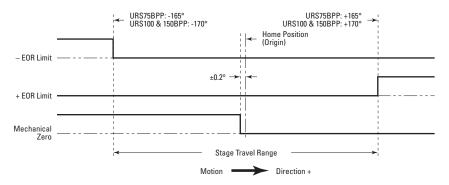
#### **NOTE**

- No End-of-Run limits on URS50B rotation stages.
- Before using a URS-B rotation stage, make sure that it is positioned close to the zero graduation in order to be properly initialized at the time of its first connection.

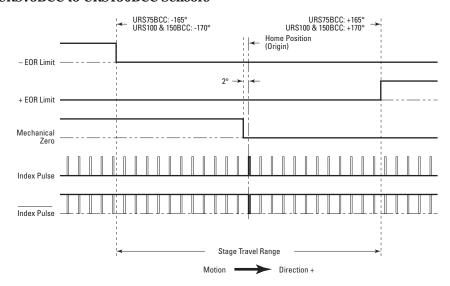
#### **URS50B Sensor**



#### **URS75BPP to URS150BPP Sensors**



# **URS75BCC to URS150BCC Sensors**



End-of-Run and Mechanical Zero are 5 V open collector type.

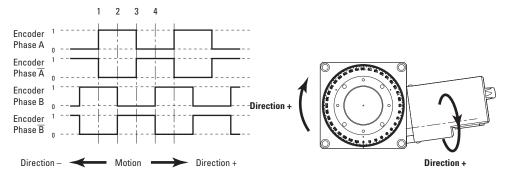
The Index Pulse provides a repeatable Home Position at ±1 step.



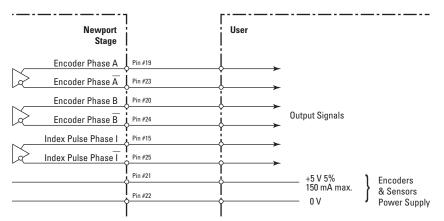
#### **CAUTION**

"End-of-Run" and "Mechanical Zero" are active signals and should not be connected to any other source.

# 5.6 Feedback Signal Position



The incremental sensor consists of a optical scale and an encoder head. When the carriages of the stage move, the encoder head generates square signals in quadrature, sent to pins #19, #20, #23 and #24 of the SUB-D25 connector.

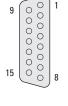


"Encoder" and "Index Pulse" are "differential pair" (type RS-422) type output signals. Using these signals permits a high immunity to noise. Emission circuits generally used by Newport are 26LS31 or MC3487. Reception circuits to use are 26LS32 or MC3486.

## 5.7 Pinouts

The SUB-D15 connection for the URS-B rotation stage is given in the following table:

URS-BPP			URS50BCC	URS	675BCC to URS150BCC
	UE28PP or UE34PP		UE18CC-R2		UE34CC
1	+ Phase 1	1	N.C.	1	N.C.
2	+ Phase 2	2	+ Motor	2	+ Motor
3	Mechanical Zero	3	Mechanical Zero	3	Mechanical Zero
4	– End-of-Run (1)	4	N.C.	4	– End-of-Run
5	0 V	5	0 V	5	0 V
6	N.C.	6	Encoder Phase /A	6	Encoder Phase /A
7	N.C.	7	Encoder Phase /B	7	Encoder Phase /B
8	N.C.	8	N.C.	8	/Index Pulse
9	- Phase 1	9	N.C.	9	N.C.
10	- Phase 2	10	– Motor	10	- Motor
11	+ End-of-Run (1)	11	N.C.	11	+ End-of-Run
12	+5 V	12	+5 V	12	+5 V
13	N.C.	13	Encoder Phase A	13	Encoder Phase A
14	N.C.	14	Encoder Phase B	14	Encoder Phase B
15	N.C.	15	N.C.	15	Index Pulse

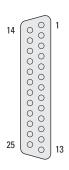






URS-BPP		URS50BCC		URS75BCC to URS150BCC	
UE28PP or UE34PP		UE18CC-R2		UE34CC	
+ Phase 1	1	N.C.	1	N.C.	
N.C.	2	N.C.	2	N.C.	
- Phase 1	3	N.C.	3	N.C.	
N.C.	4	N.C.	4	N.C.	
+ Phase 2	5	+ Motor	5	+ Motor	
N.C.	6	+ Motor	6	+ Motor	
- Phase 2	7	– Motor	7	– Motor	
N.C.	8	– Motor	8	– Motor	
N.C.	9	N.C.	9	N.C.	
N.C.	10	N.C.	10	N.C.	
N.C.	11	N.C.	11	N.C.	
N.C.	12	N.C.	12	N.C.	
Mechanical Zero	13	Mechanical Zero	13	Mechanical Zero	
N.C.	14	Shield Ground	14	Shield Ground	
N.C.	15	N.C.	15	Index Pulse I	
N.C.	16	0 V Logic	16	0 V Logic	
				* . = * 5- *	
+ End-of-Run (1)	17	N.C.	17	+ End-of-Run	
+ End-of-Run (1)  - End-of-Run (1)	17 18	N.C.	17 18		
			_	+ End-of-Run	
– End-of-Run (1)	18	N.C.	18	+ End-of-Run – End-of-Run	
– End-of-Run <sup>(1)</sup> N.C.	18 19	N.C. Encoder Phase A	18 19	+ End-of-Run – End-of-Run Encoder Phase A	
– End-of-Run <sup>(1)</sup> N.C. N.C.	18 19 20	N.C. Encoder Phase A Encoder Phase B	18 19 20	+ End-of-Run  – End-of-Run  Encoder Phase A  Encoder Phase B	
– End-of-Run <sup>(1)</sup> N.C. N.C. +5 V	18 19 20 21	N.C. Encoder Phase A Encoder Phase B +5 V	18 19 20 21	+ End-of-Run  - End-of-Run  Encoder Phase A  Encoder Phase B  +5 V	
– End-of-Run <sup>(1)</sup> N.C. N.C. +5 V 0 V	18 19 20 21 22	N.C. Encoder Phase A Encoder Phase B +5 V 0 V Encoder	18 19 20 21 22	+ End-of-Run  - End-of-Run  Encoder Phase A  Encoder Phase B  +5 V  0 V Encoder	
	UE28PP or UE34PP  + Phase 1  N.C.  - Phase 1  N.C.  + Phase 2  N.C.  - Phase 2  N.C.  N.C.	UE28PP or UE34PP         + Phase 1       1         N.C.       2         - Phase 1       3         N.C.       4         + Phase 2       5         N.C.       6         - Phase 2       7         N.C.       8         N.C.       9         N.C.       10         N.C.       11         N.C.       12         Mechanical Zero       13         N.C.       14         N.C.       15	UE28PP or UE34PP         UE18CC-R2           + Phase 1         1         N.C.           N.C.         2         N.C.           - Phase 1         3         N.C.           N.C.         4         N.C.           + Phase 2         5         + Motor           N.C.         6         + Motor           - Phase 2         7         - Motor           N.C.         8         - Motor           N.C.         9         N.C.           N.C.         10         N.C.           N.C.         11         N.C.           N.C.         12         N.C.           Mechanical Zero         13         Mechanical Zero           N.C.         14         Shield Ground           N.C.         15         N.C.	UE28PP or UE34PP         UE18CC-R2           + Phase 1         1         N.C.         1           N.C.         2         N.C.         2           - Phase 1         3         N.C.         3           N.C.         4         N.C.         4           + Phase 2         5         + Motor         5           N.C.         6         + Motor         6           - Phase 2         7         - Motor         7           N.C.         8         - Motor         8           N.C.         9         N.C.         9           N.C.         10         N.C.         10           N.C.         11         N.C.         11           N.C.         11         N.C.         12           Mechanical Zero         13         Mechanical Zero         13           N.C.         14         Shield Ground         14           N.C.         15         N.C.         15	





# **Connection to Newport Controllers**

### 6.1 Warnings on Controllers

Controllers are intended for use by qualified personnel who recognize shock hazards and are familiar with safety precautions required to avoid possible injury. Read the controller user's manual carefully before operating the instrument and pay attention to all written warnings and cautions.

#### **WARNING**

Disconnect the power plug under the following circumstances:

- If the power cord or any attached cables are frayed or damaged in any way.
- If the power plug is damaged in any way.
- If the unit is exposed to rain, excessive moisture, or liquids are spilled on the unit.
- If the unit has been dropped or the case is damaged.
- If you suspect service or repair is required.
- Whenever you clean the electronics unit.

#### **CAUTION**

To protect the unit from damage, be sure to:

- Keep all air vents free of dirt and dust.
- Keep all liquids away from the unit.
- Do not expose the unit to excessive moisture (85% humidity).

• Read this manual before using the unit for the first time.



# WARNING

All attachment plug receptacles in the vicinity of this unit are to be of the grounding type and properly polarized.

Contact your electrician to check your receptacles.

# **WARNING**

This product is equipped with a 3-wire grounding type plug.

Any interruption of the grounding connection can create an electric shock hazard.

If you are unable to insert the plug into your wall plug receptacle, contact your electrician to perform the necessary alterations to ensure that the green (green-yellow) wire is attached to earth ground.

# WARNING

This product operates with voltages that can be lethal.

Pushing objects of any kind into cabinet slots or holes, or spilling any liquid on the product, may touch hazardous voltage points or short out parts.

#### 6.2 Connection

On each stage is represented a label which indicates its name and its serial number.



#### **WARNING**

Always turn the controller's power OFF before connecting to a stage.

Stages may be connected to the rear panel motor connectors any time prior to power-up with the supplied cable assemblies.

#### **NOTE**

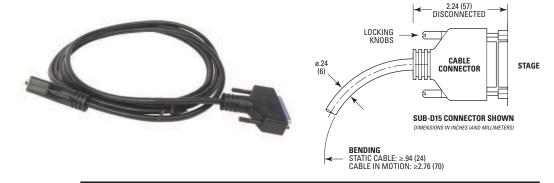


These stages are ESP compatible. Enhanced System Performance is Newport's exclusive technology that enables Newport ESP motion controllers to recognize the connected Newport ESP stage and upload the stage parameters. This ensures that the user can operate the motion system quickly and safely.

#### 6.3 Cables

Our stages are delivered with a **MSCABLE-3** 3-meter cable. This cable is equipped with SUB-D15F and SUB-D25M connectors so it can be directly connected to our controllers/drivers.

#### 6.4 MSCABLE-3 Cable





## **WARNING**

This cable is shielded correctly. For a correct operation, make sure to lock connectors (ground continuity provided by the cable).

For applications where the standard 3-meter cable (MSCABLE-3) included with your stage is not adequate, Newport offers a 10-m longer length cable (MSCABLE-10) designed to ensure the integrity of your positioning application.

These cables are specially shielded and terminated with Newport's standard SUB-D15 and SUB-D25 connectors.



# WARNING

Keep the motor cables at a safe distance from other electrical cables in your environment to avoid potential cross talk.

# **Connection to Non-Newport Electronics**

#### 7.1 Connections

### **WARNING**

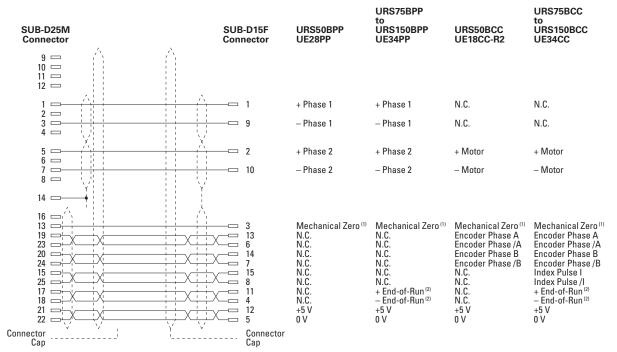


Newport is not responsible for malfunction or damage to a URS-B stage when it is used with non-Newport controllers.

# WARNING

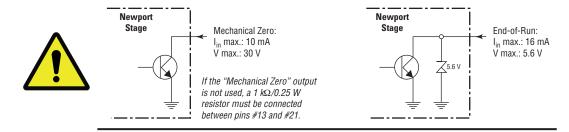
Newport guarantees "( compliance of the URS-B stage only if they are used with Newport cables and controllers.

Nevertheless, the figure below shows the wiring when a URS-B stage is used with non-Newport controllers.



 $<sup>^{(1)}</sup>$  The Mechanical Zero logic signal is open collector type. It supports until 30 V and 10 mA.

<sup>(2)</sup> Open collector type with a 5.6 V protective Zener diode.



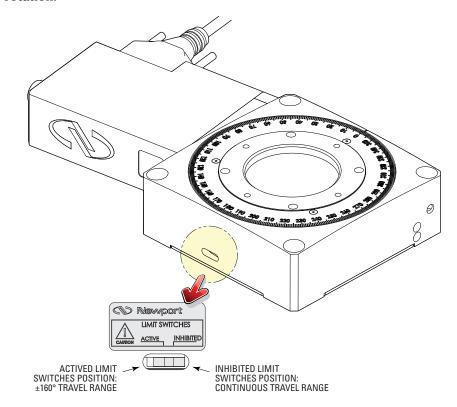
"Encoder" and "Index Pulse" are "differential pair" (type RS-422) type output signals. Using these signals permits a high immunity to noise. Emission circuits generally used by Newport are 26LS31 or MC3487. Reception circuits to use are 26LS32 or MC3486.

# **Disabling of Limit Switches**

### **NOTE**

# No End-of-Run limits on URS50B rotation stages.

Except URS50B stages, all other URS-B stages are equipped with  $\pm 160^\circ$  optical limit switches. These limit switches can be disabled for continuous  $360^\circ$  rotation.



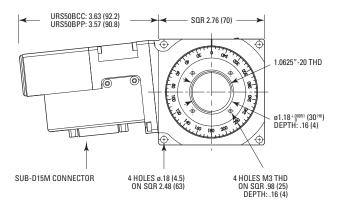
# **NOTE**

On request, these limit switches can be set in factory at the desired position. Please contact our sales engineers.

The limit switches default position is  $\pm 160^{\circ}$ .

# **Dimensions**

# 9.1 URS50B Stages





MODEL SHOWN: URS50BCC DIMENSIONS IN INCHES (AND MILLIMETERS)



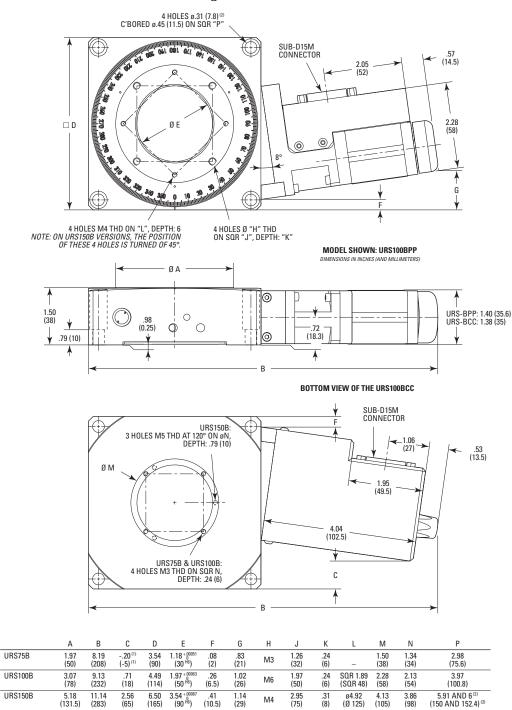
URS50BPP URS50BCC



**NOTE** 

URS50B rotation stages are equipped with a hole for grounding M3 THD, usable depth: .24 (6).

#### 9.2 **URS75B to URS150B Stages**



NOTES:
"I THE DRIVE BOX OF THE URS75BCC EXCEEDS .20 IN. (5 MM) FROM THE BODY.
"I URS150B: 4 SLOTS COUNTERBORED.





URS100BCC

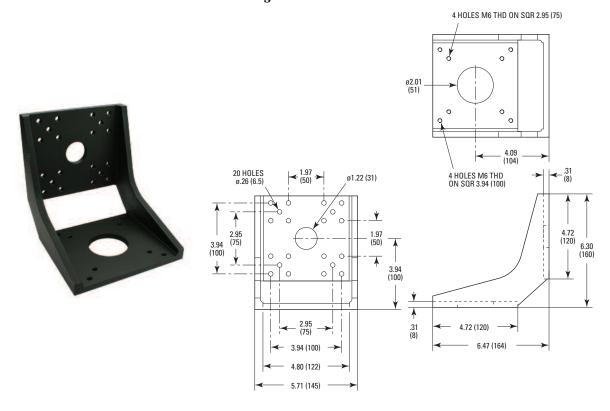


# Accessories

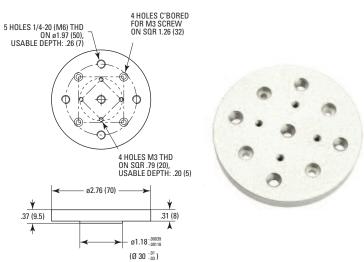
# **NOTE**

The following accessories are not included with URS-B Series rotation stages and must be ordered separately.

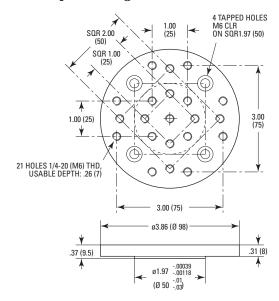
# 10.1 URSBK: 90° Mounting Bracket for URS-B Series



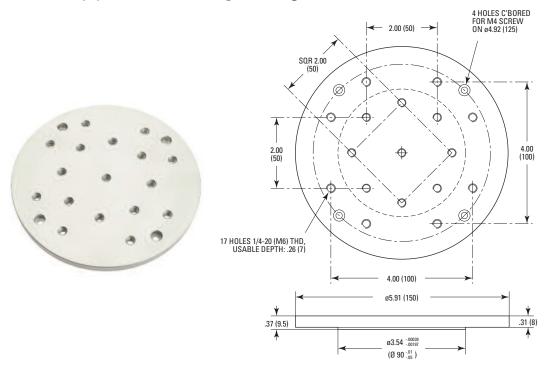
# 10.2 (M-)URS75TP: Solid Top Mounting Plate for URS75B



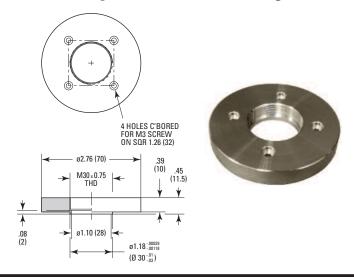
# 10.3 (M-)URS100TP: Solid Top Mounting Plate for URS100B



# 10.4 (M-)URS150TP: Solid Top Mounting Plate for URS150B



# 10.5 URS75P1: 1" Diameter Optics Holder for URS75B Stages



#### **Maintenance**

#### RECOMMENDATION

It is recommended to contact our After Sales Service which will know to define the appropriate maintenance for your application.

#### 11.1 Maintenance

The URS-B stage requires no particular maintenance. Nevertheless, this is a precision mechanical device that must be kept and operated with caution.

#### **PRECAUTIONS**

The URS-B stage must be used or stocked in a clean environment, without dust, humidity, solvents or other substances.

#### RECOMMENDATION

It is recommended to return your URS-B stage to Newport's After Sales Service after every 2000 hours of use for lubrication.

If your stage is mounted on a workstation and cannot be easily removed, please contact Newport's After Sales Service for further instructions.

### 11.2 Repair



#### **CAUTION**

Never attempt to disassemble a component of the stage that has not been covered in this manual.

To disassemble a non specified component can cause a malfunction of the stage.

If you observe a malfunction in your stage, please contact us immediately to arrange for a repair.



# **CAUTION**

Any attempt to disassemble or repair a stage without prior authorization will void your warranty.

#### 11.3 Calibration



#### **CAUTION**

It is recommended to return your URS-B stage to Newport once a year for recalibration to its original specifications.

# **Service Form**

Name:	Return authorization #:
	(Please obtain prior to return of item)
Company:	
Address:	
Country:	
P.O. Number:	Fax Number:
Item(s) Being Returned:	
Model #:	Serial #:
Description:	
Reasons of return of goods (please list	any specific problems):

**Your Local Representative** 

Fax: \_\_\_\_



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# North America & Asia

Newport Corporation 1791 Deere Ave. Irvine, CA 92606, USA

## **Sales**

Tel.: (800) 222-6440

e-mail: sales@newport.com

# **Technical Support**

Tel.: (800) 222-6440

e-mail: tech@newport.com

# Service, RMAs & Returns

Tel.: (800) 222-6440

e-mail: service@newport.com

# **Europe**

MICRO-CONTROLE Spectra-Physics S.A.S

9, rue du Bois Sauvage 91055 Évry CEDEX France

# **Sales & Technical Support**

Tel.: +33 (0)1.60.91.68.68

e-mail: france@newport.com

# **Service & Returns**

Tel.: +33 (0)2.38.40.51.55